
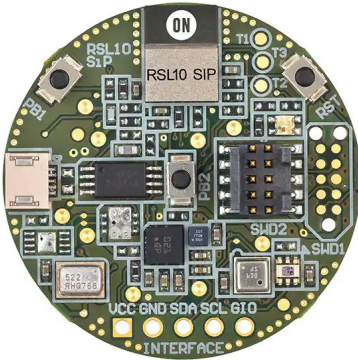
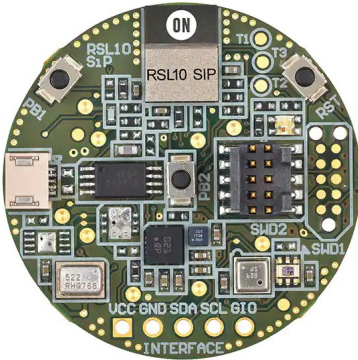


# onsemi\* – RSL10 Multi-Protocol Bluetooth\* System-on-Chip

<p><b>SensiML Supported Development Kit</b></p>	<p><b>Processor</b></p>	<p>RSL10 Radio SIP, Arm* Cortex-M3 + low power DSP, 32-bit with Bluetooth 5.2 (<a href="#">RSL10</a>)</p>
<p>onsemi RSL10-SIP-001GEVB: RSL10 SIP Development Board</p> 	<p><b>Pre-enabled Sensor Types</b></p>	<p><a href="#">Bosch* BHI160</a> 6DoF accel + gyro</p>
	<p><b>Additional Available Sensors</b></p>	<p><a href="#">NOA1305 Ambient Light Sensor</a>, <a href="#">Bosch BMM150</a> magnetometer, <a href="#">Bosch BME680</a> environmental sensor, <a href="#">INMP522</a> digital microphone</p>
<p>onsemi RSL10 SENSE-GEVK / SENSE-DB-GEVK</p>	<p><b>Available External Sensor Interfaces</b></p>	<p>I2C (SENSE-GEVK) UART, I<sup>2</sup>C, SPI, PCM (RSL10 SIP)</p>
	<p><b>Pre-enabled Connectivity</b></p>	<p>Bluetooth LE wireless</p>
<p>RSL10-SENSE-DB-GEVK: RSL10 Sensor Development Kit</p>	<p><b>Programming Environment</b></p>	<p>IDEs: <a href="#">Eclipse* based onsemi IDE</a> Compilers: Arm Embedded GCC 10.2.1</p>
	<p><b>Firmware Flashing</b></p>	<p>Requires RSL10-SIP-001GEVB (which has an onboard Segger* J-Link* debugger plus a <a href="#">10-pin JTAG ribbon cable</a>)*</p>
	<p><b>SensiML Knowledge Pack Formats</b></p>	<p><a href="#">Library</a>, <a href="#">C Source</a></p>
	<p><b>Useful Links</b></p>	<p><a href="#">SensiML Getting Started Guide</a>, <a href="#">HW Getting Started Guide</a>, <a href="#">Robotics Motion Recognition Demo</a></p>